

E SERIES

SV4E-DPRXG

MIPI D-PHY Frame Grabber



Any-Rate, Any-Resolution MIPI CSI-2 Sensor Calibration and Characterization Solution

The SV4E-DPRXG MIPI D-PHY Frame Grabber is a flexible solution for capturing and analyzing MIPI® Alliance CSI-2® sensor data. It can be attached to any CSI-2 camera output or radar output, and it will automatically extract image data and support automated application development, calibration, and regression testing. The SV4E-DPRXG's unique analog front-end technology for the MIPI Alliance D-PHYSM physical layer means that users can achieve high-confidence sensor validation without worrying about physical attachment issues.

KEY FEATURES:

- **D-PHY Physical Layer:** Monolithic receiver with integrated LP/HS signaling and support for data rates up to 3.5 Gbps per lane.
- **CSI-2 Controller:** Support for all CSI-2 data types and pixel formats, including RAW16 and RAW20.
- **Virtual Channels:** Automatic extraction of all virtual channels supported by the CSI-2 standard.
- **I2C and I3C Master:** Dual-mode I2C/I3C master for controlling sensors and providing true host-emulation capability.
- **Diagnostics:** Built-in frame-rate and CRC monitors.

KEY BENEFITS:

- **Future-Proof:** High-performance receiver that is upgradable – within the same hardware – to include packet and protocol analysis.
- **Self-Contained:** An all-in-one system reduces bench space and helps create very compact regression farms.
- **Flexible:** Live streaming mode helps with manual sensor setup, and bulk capture mode helps with automation.
- **Automated:** Leverages the full power of Python and the award-winning Pinetree software.

Typical Application: CSI-2 D-PHY Sensor Calibration and Characterization



Simple Connection with DUT Directly Mounted

```

17 i2cWrite(slaveAddr, slaveReg=0x5412, regAddrLen=0, regAddrEndianness='big', msgBytes=[0x01])
18
19 # SET DEFAULT EXPOSURE
20 i2cWrite(slaveAddr, slaveReg=0x4400, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x04])
21 i2cWrite(slaveAddr, slaveReg=0x4401, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x04])
22 i2cWrite(slaveAddr, slaveReg=0x4402, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x04])
23
24 # START STREAMER
25 mipiCphyCsIstreamer1.start()
26
27 # CAPTURE TEST PATTERN
28 print("TEST PATTERN ENABLE")
29 i2cWrite(slaveAddr, slaveReg=0x6800, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x00])
30 sleepMills(50)
31 testPatternFrame1 = mipiCphyCsIstreamer1.getFrame()
32 i2cWrite(slaveAddr, slaveReg=0x6800, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x00])
33 sleepMills(50)
34
35 # ENABLE VERTICAL AND HORIZONTAL FLIP
36 i2cWrite(slaveAddr, slaveReg=0x4820, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x10])
37 print("VERTICAL FLIP ON"); sleepMills(100)
38 verticalFrameFlipOn = mipiCphyCsIstreamer1.getFrame()
39 i2cWrite(slaveAddr, slaveReg=0x4820, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x00])
40 print("VERTICAL FLIP OFF"); sleepMills(100)
41 verticalFrameFlipOff = mipiCphyCsIstreamer1.getFrame()
42 i2cWrite(slaveAddr, slaveReg=0x4821, regAddrLen=2, regAddrEndianness='big', msgBytes=[0x04])
43 print("HORIZONTAL FLIP ON"); sleepMills(100)
44 horizontalFrameFlipOn = mipiCphyCsIstreamer1.getFrame()

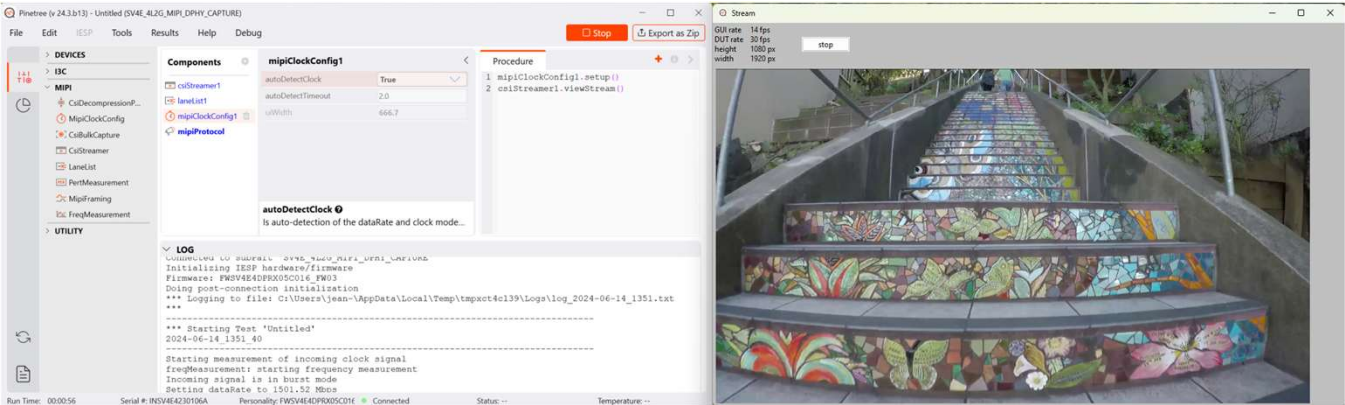
```

Highly Flexible Automation Environment

Key Performance Parameters

PARAMETER	VALUE	NOTES
Number of Lanes	4 Data + 1 Clock	Adjustable lane configuration; supports D-PHY v2.5 signaling
Symbol Rates	80 Msps – 3.5 Gbps	Supports a wide array of sensors
Minimum $ V_{OD} $	140 mV	Measured at module connector
Maximum $ V_{OD} $	300 mV	Measured at module connector
Minimum T_{LPX}	50 ns	
Minimum $T_{HS-PREPARE} + T_{HS-ZERO}$	145 ns + 10 UI	
Total Memory Space	1 GByte	Entire memory space is available for captured image storage
Number of Programmable Power Supplies	6	Independently controlled through Python scripting
Programmable Power Supply Parameters	1 V – 5 V in steps of 1 mV	Each power supply provides 3 A

Use the SV4E-DPRXG Frame Grabber with Pinetree to Stream CSI-2 Sensor Data



The screenshot displays the Pinetree software interface. On the left, a sidebar shows the 'DEVICES' list with 'MIPI' selected. The main window is divided into three panes: 'Components' (showing 'mipiClockConfig1' with settings like 'autoDetectClock' and 'laneList'), 'Procedure' (showing a list of steps), and 'LOG' (showing a detailed log of the device's initialization and operation). On the right, a 'Stream' window shows a live video feed of a staircase with colorful graffiti, with a 'stop' button and stream statistics (Gbit rate, Out rate, height, width).

Dynamically Visualizing Sensor Response and Sensitivity During Live Streaming